

**WHAT IS CLAIMED:**

1. A method for adaptive channel estimation for a digital wireless rake receiver having a plurality of finger signals comprising the following steps:
  - calculating pilot integration window as a function of Doppler period;
  - 5 wherein the Doppler period is inverse of Doppler frequency.
2. The method as recited in claim 1 further comprising the step of calculating a symmetric integration window approximately 13% of the Doppler period.
- 10 3. The method as recited in claim 1 further comprising the step of calculating an asymmetric integration window approximately 3% of the Doppler period.
4. The method as recited in claim 1 wherein the pilot integration window is a function of Rician parameter.
- 15 5. The method as recited in claim 1 wherein the pilot integration window is a function of interference level.
6. The method as recited in claim 1 wherein a corresponding pilot integration 20 window is calculated separately for each of the plurality of fingers.

7. A digital radio system for receiving a plurality of signals, comprising:  
a digital wireless rake receiver having a plurality of finger signals;  
means for calculating pilot integration window as a function of Doppler period;  
wherein the Doppler period is inverse of Doppler frequency.

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8. The digital radio system as recited in claim 7 wherein a symmetric integration window is approximately 13% of the Doppler period.

9. The digital radio system as recited in claim 7 wherein an asymmetric integration window is approximately 3% of the Doppler period.

10. The digital radio system as recited in claim 7 wherein the pilot integration window is a function of Rician parameter.

15 11. The digital radio system as recited in claim 7 wherein the pilot integration window is a function of interference level.

12. The digital radio system as recited in claim 7 wherein a corresponding pilot integration window is calculated separately for each of the plurality of fingers.

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13. A signal processor for a digital wireless receiver having a plurality of signals, the signal processor comprising:

a processing circuit for processing the plurality of signals and providing a processed signal, wherein a pilot integration window is calculated as a function of Doppler period.

5 14. The signal processor as recited in claim 13 wherein a symmetric integration window is calculated as approximately 13% of the Doppler period.

15. The signal processor as recited in claim 13 wherein an asymmetric integration window is calculated as approximately 3% of the Doppler period.

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16. The signal processor as recited in claim 13 wherein the pilot integration window is calculated as a function of Rician parameter.

17. The signal processor as recited in claim 13 wherein the pilot integration window 15 is calculated as a function of interference level.

18. The signal processor as recited in claim 13 wherein a corresponding pilot integration window is calculated separately for each of the plurality of fingers.

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